Minimum rank of skew-symmetric matrices described by a graph^{*}

IMA-ISU research group on minimum rank [†]

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Abstract

The minimum (symmetric) rank of a simple graph G over a field F is the smallest possible rank among all symmetric matrices over F whose ijth entry (for $i \neq j$) is nonzero whenever $\{i, j\}$ is an edge in G and is zero otherwise. The problem of determining minimum (symmetric) rank has been studied extensively. We define the minimum skew rank of a simple graph G to be the smallest possible rank among all skew-symmetric matrices over F whose ijth entry (for $i \neq j$) is nonzero whenever $\{i, j\}$ is an edge in G and is zero otherwise. We apply techniques from the minimum (symmetric) rank problem and from skew-symmetric matrices to obtain results about the minimum skew rank problem.

Keywords. minimum rank, minimum skew rank, skew-symmetric matrix, matching, pfaffian, rank, graph, matrix.

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1 Introduction

The classic minimum rank problem involves real symmetric matrices described by a graph. This problem has been studied extensively and generalized to symmetric matrices over other fields; see [9] for a survey of known results and a discussion of the motivation for the minimum rank problem. In this paper, we study the problem of determining the minimum rank of skew-symmetric matrices described by a graph.

If a field F is of characteristic 2, then the skew-symmetric matrices are the same as the symmetric matrices. Thus it is assumed throughout this paper that **the fields under consideration do not have characteristic** 2.

1.1 Notation and Terminology

An $n \times n$ matrix A over a field F is *skew-symmetric* (respectively, *symmetric*) if $A^T = -A$ ($A^T = A$); for $A \in \mathbb{C}^{n \times n}$, A is *Hermitian* if $A^* = A$, where A^* denotes the conjugate transpose of A.

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A graph is a pair $G = (V_G, E_G)$, where V_G is the (finite, nonempty) set of vertices of G (usually $\{1, \ldots, n\}$ or a subset thereof) and E_G is the set of edges (two-element subsets of vertices). These graphs are usually called simple undirected graphs. The *order* of a graph G, denoted |G|, is the number of vertices of G.

For a symmetric, skew-symmetric or Hermitian matrix, the graph of an $n \times n$ matrix A, denoted $\mathcal{G}(A)$, is the graph with vertices $\{1, \ldots, n\}$ and edges $\{\{i, j\}: a_{ij} \neq 0, 1 \leq i < j \leq n\}$. Note that the diagonal is ignored in determining $\mathcal{G}(A)$ for symmetric and Hermitian matrices (the diagonal must be 0 for a skew-symmetric matrix).

The set of symmetric matrices over a field F described by G is

$$\mathcal{S}(F,G) = \{ A \in F^{n \times n}, \ A^T = A, \ \mathcal{G}(A) = G \}.$$

The minimum rank of a graph G over F is $mr(F,G) = min\{rank A : A \in \mathcal{S}(F,G)\}$, and the maximum nullity of G over F is $M(F,G) = max\{null(A) : A \in \mathcal{S}(F,G)\}$. Clearly mr(F,G) + M(F,G) = |G|. When the field is omitted it is assumed to be the real field, e.g., $mr(G) = mr(\mathbb{R},G)$.

The set of skew-symmetric matrices over F described by G is

$$\mathcal{S}^{-}(F,G) = \{ A \in F^{n \times n} : A^T = -A, \ \mathcal{G}(A) = G \}.$$

The minimum skew rank of a graph G over F is defined to be

$$\operatorname{mr}^{-}(F,G) = \min\{\operatorname{rank} A : A \in \mathcal{S}^{-}(F,G)\},\$$

and the maximum skew nullity of G over F is defined to be

$$\mathcal{M}^{-}(F,G) = \max\{\mathcal{null}(A) : A \in \mathcal{S}^{-}(F,G)\}.$$

Clearly $\operatorname{mr}^{-}(F,G) + \operatorname{M}^{-}(F,G) = |G|$. We say the matrix $A \in F^{n \times n}$ is optimal for G (over F) if $A \in \mathcal{S}^{-}(F,G)$ and rank $A = \operatorname{mr}^{-}(F,G)$.

Clearly the maximum rank among matrices in $\mathcal{S}(F,G)$ is |G|, but this need not be the case for skew rank. The maximum skew rank of a graph G is

$$\mathrm{MR}^{-}(F,G) = \max\{\mathrm{rank}\,A: A \in \mathcal{S}^{-}(F,G)\}.$$

The set of Hermitian matrices described by G is

$$\mathcal{H}(G) = \{ A \in \mathbb{C}^{n \times n}, \ A^* = A, \ \mathcal{G}(A) = G \}.$$

The minimum Hermitian rank of a graph G is $hmr(G) = min\{rank A : A \in \mathcal{H}(G)\}$. Minimum Hermitian rank has been studied in [5], and is a lower bound on the skew rank (over the real field).

The subgraph G[R] of G induced by $R \subseteq V_G$ is the subgraph with vertex set R and edge set $\{\{i, j\} \in E_G \mid i, j \in R\}$. The subdigraph induced by $V_G \setminus R$ is also denoted by G - R, or in the case $R = \{v\}$, by G - v. If A is an $n \times n$ matrix and $R \subseteq \{1, \ldots, n\}$, the principal submatrix A[R] is the matrix consisting of the entries in the rows and columns indexed by R, and A(R) is the complementary principal submatrix obtained from A by deleting the rows and columns indexed by R. In the special case when $R = \{k\}$, we use A(k) to denote A(R). If $A \in S^-(F, G)$, then by a slight abuse of notation $\mathcal{G}(A[R])$ can be identified with G[R].

The adjacency matrix of G, $A_G = [a_{ij}]$, is a 0,1-matrix such that $a_{ij} = 1$ if and only if $\{i, j\} \in E_G$. The formal skew adjacency matrix of G is $X_G = A_G \circ X$ where X is a skew-symmetric matrix having ij-entry x_{ij} for i < j, x_{ij} are independent indeterminates, and \circ denotes the Hadamard (entrywise) product.

A path, cycle, complete graph, and complete multipartite graph will be denoted by P_n, C_n, K_n , and $K_{n_1,n_2,...n_t}$ $(t \ge 2, n_i \ge 1)$, respectively.

The complement of a graph G = (V, E) is the graph $\overline{G} = (V, \overline{E})$, where \overline{E} consists of all twoelement sets of V that are not in E. The union of $G_i = (V_i, E_i)$ is $\bigcup_{i=1}^h G_i = (\bigcup_{i=1}^h V_i, \bigcup_{i=1}^h E_i)$; a disjoint union is denoted $\bigcup_{i=1}^h G_i$. The intersection of $G_i = (V_i, E_i)$ is $\bigcap_{i=1}^h G_i = (\bigcap_{i=1}^h V_i, \bigcap_{i=1}^h E_i)$. The join $G \vee G'$ of two disjoint graphs G = (V, E) and G' = (V', E') is the union of $G \cup G'$ and the complete bipartite graph with vertex set $V \cup V'$ and partition $\{V, V'\}$. A cut-vertex is a vertex whose deletion increases the number of connected components.

A matching in a graph G is a set of edges $\{i_1, j_1\}, ..., \{i_k, j_k\}$ such that all the vertices are distinct. A perfect matching in a graph G is a matching that includes all vertices of G. A maximum matching in G is a matching with the maximum number of edges among all matchings in G. The matching number, denoted match(G), is the number of edges in a maximum matching.

An important matrix function in the study of matchings is the pfaffian (see [12] for more details). Let $L = \{\{i_1, i_2\}, \ldots, \{i_{n-1}, i_n\}\}$ be a perfect matching in G, ordered so that $i_1 < i_2, i_3 < i_4, \ldots, i_{n-1} < i_n$ and $i_1 < i_3 < \cdots < i_{n-1}$. Let π_L be the permutation of $\{1, \ldots, n\}$ that maps k to i_k . For $A \in S^-(F, G)$, the weight of L with respect to A is

$$\operatorname{wt}_A(L) = \operatorname{sgn}(\pi_L) a_{i_1, i_2} \dots a_{i_{n-1}, i_n},$$

where $sgn(\pi)$ is the sign of the permutation π . Let \mathcal{F} be the set of all perfect matchings of G. The *pfaffian* of A is

$$\operatorname{pf}(A) = \sum_{L \in \mathcal{F}} \operatorname{wt}_A(L),$$

where the sum over the empty set is 0.

1.2 Known results about matchings and skew-symmetric matrices

This subsection contains results that will be used in the next section; throughout F denotes a field (which, as we have already mandated, does not have characteristic 2). The proof of the next result is similar to the proof for the symmetric case (cf. [10, Theorem 8.9.1])

Theorem 1.1. Let $A \in F^{n \times n}$ be skew-symmetric. Then rank $A = \max\{|S| : \det(A[S]) \neq 0\}$.

Corollary 1.2. The rank of any skew-symmetric matrix over F is even.

The proof of the next result is similar to the proof for the symmetric case (cf. [10, Lemma 8.9.3]).

Lemma 1.3. For a nonzero skew-symmetric matrix $A \in F^{n \times n}$, rank $A \leq 2k$ if and only if there

exist
$$\mathbf{x}_1, \dots, \mathbf{x}_k, \mathbf{y}_1, \dots, \mathbf{y}_k \in F^n$$
 such that $A = \sum_{i=1}^n (\mathbf{x}_i \mathbf{y}_i^T - \mathbf{y}_i \mathbf{x}_i^T).$

Theorem 1.4. [6, Theorem 9.5.2] If $A \in F^{n \times n}$ is skew-symmetric, then det $A = (pf(A))^2$.

Corollary 1.5. Let $A \in F^{n \times n}$ be skew-symmetric. If $\mathcal{G}(A)$ has a unique perfect matching then rank A = n.

Let M be a matching of a graph G(V, E) An M-alternating path is a path in G where the edges in the path alternate between edges in $E \setminus M$ and edges in M. An M-augmenting path is a M-alternating path in G where the first and last edges of the path are in $E \setminus M$. The following theorem of Berge is well known.

Theorem 1.6. [13, p. 109] A matching M in a graph G is a maximum matching in G if and only if G has no M-augmenting path.

Graphs with unique perfect matching have been characterized in [12, Cor 5.3.12].

The statements in Observation 1.7 follow immediately from the preceding results or are established by applying the same methods used for the analogous results in the symmetric minimum rank problem.

Observation 1.7.

1. $mr^{-}(F,G)$ and $MR^{-}(F,G)$ are always even.

- 2. If G has a unique perfect matching then $mr^{-}(F,G) = |G|$.
- 3. If H is an induced subgraph of G, then $mr^{-}(F, H) \leq mr^{-}(F, G)$.
- 4. $mr^{-}(F,G) = 0$ if and only if G has no edges.
- 5. If the connected components of G are G_1, \ldots, G_t , then

$$\operatorname{mr}^{-}(F,G) = \sum_{i=1}^{t} \operatorname{mr}^{-}(F,G_i).$$

2 Results derived from the properties of skew-symmetric matrices

In this section we use properties specific to skew-symmetric matrices to obtain results about minimum skew rank. All of the results in this section are valid over any infinite field. Most are valid for finite fields, but some technical results about polynomials over finite fields are needed for the proofs; these are included in the Appendix (Section 6).

Theorem 2.1. Let G be a connected graph with $|G| \ge 2$ and let F be an infinite field. Then the following are equivalent:

- 1. $mr^{-}(F,G) = 2$,
- 2. $G = K_{n_1, n_2, \dots, n_t}$ for some $t \ge 2, n_i \ge 1, i = 1, \dots, t$,
- 3. G does not contain P_4 or the paw (see Figure 1) as an induced subgraph.

Without the assumption that G is connected, $mr^{-}(F,G) = 2$ if and only if G is a union of one $K_{n_1,n_2,...,n_t}$ and possibly some isolated vertices.





Proof. $(2 \Longrightarrow 1)$ Let $G = K_{n_1,n_2,\dots,n_t} = (V_1 \cup \dots \cup V_t, E)$ where the sets V_k $(k = 1,\dots,t)$ are the partite sets, and let $n = \sum_{i=1}^t n_i$. Let $\alpha_1, \dots, \alpha_t$ be distinct elements of F. Construct $\mathbf{x}, \mathbf{y} \in F^n$ such that $x_i = 1$ for all i and $y_j = \alpha_k$ for each vertex j in V_k . Observe that by construction the matrix $A = \mathbf{x}\mathbf{y}^T - \mathbf{y}\mathbf{x}^T$ is a skew-symmetric matrix with rank A = 2. If vertex i is in partite set V_k and vertex j is in partite set V_ℓ , then $a_{ij} = \alpha_\ell - \alpha_k$, and thus $a_{ij} = 0$ if and only if vertices i and j are in the same partite set. It follows that $\mathcal{G}(A) = K_{n_1,n_2,\dots,n_t}$. Since $A \in \mathcal{S}^-(F,G)$ and rank A = 2, we conclude that $\mathrm{mr}^-(F,G) = 2$.

 $(1 \Longrightarrow 3)$ This follows from Observation 1.7 since P_4 and the paw each have a unique perfect matching.

 $(3 \Longrightarrow 2)$ Suppose that G is not a complete multipartite graph. Then $|G| \ge 4$ and G contains $K_2 \dot{\cup} K_1$ as an induced subgraph. Let H be the smallest connected induced subgraph of G that contains $K_2 \dot{\cup} K_1$ as an induced subgraph. Note that since H is connected, but has the induced subgraph $K_2 \dot{\cup} K_1$, we know that $|H| \ge 4$.

We show that if |H| > 4, then H is not the smallest such graph. Label the vertices of an induced $K_2 \dot{\cup} K_1$ by x, y, z with x and y adjacent. Since H is connected, there is a path from one of x or y to z that does not include the other (say x). Label the additional vertices on this path w_1, \ldots, w_k . See Figure 2 for the labeling, but note that this subgraph need not be an induced subgraph of G. By the minimality of H, z is not adjacent to w_1 . Then the subgraph induced by y, w_1, \ldots, w_k, z is a smaller connected induced subgraph containing an induced $K_2 \dot{\cup} K_1$.



Figure 2: A path in the induced subgraph H that contains $K_2 \dot{\cup} K_1$

So $H = G[\{x, y, w_1, z\}]$, H contains the edges $\{x, y\}, \{y, w_1\}, \{w_1, z\}$ and H does not contain the edges $\{x, z\}$ or $\{y, z\}$. If $\{x, w_1\} \in E_H$, then H is the paw; if not $H = P_4$. Therefore if $G \neq K_{n_1, n_2, \dots, n_t}$, then G must contain P_4 or the paw as an induced subgraph.

The result for disconnected graphs then follows from Observation 1.7.5.

Note that $K_n = K_{1,1,\dots,1}$ and $G = K_{n_1,\dots,n_t}$ if and only if $\overline{G} = K_{n_1} \cup \cdots \cup K_{n_t}$. For connected graphs, the implications $(1) \Rightarrow (3) \Leftrightarrow (2)$ have been established independently of field, and the proof that $\operatorname{mr}^-(F, K_{n_1,\dots,n_t}) = 2$ is clearly valid for any field with at least t elements. This need not be true for a finite field with too few elements, as the next example shows.

Example 2.2. $\operatorname{mr}^{-}(\mathbb{Z}_3, K_5) = 4$, as can be seen by computing the rank of every matrix in $\mathcal{S}^{-}(\mathbb{Z}_3, K_5)$ (there are 2^{10} such matrices).

The following corollary generalizes this example.

Corollary 2.3. In a finite field F of order q, the following are equivalent.

- 1. G is connected and $mr^{-}(F,G) = 2$.
- 2. $G = K_{n_1, n_2, \dots, n_t}$, where $2 \le t \le q+1$.

Proof. $(2 \Longrightarrow 1)$ Assume that $G = K_{n_1,n_2,\ldots,n_t}$ with $2 \le t \le q+1$. In order to construct a matrix of rank 2 in $\mathcal{S}^-(F,G)$, we first notice that $(\mathbf{x}\mathbf{y}^T - \mathbf{y}\mathbf{x}^T)_{ij} = x_iy_j - y_ix_j$ is nonzero if and only if the nonzero vectors $[x_i, y_i]$ and $[x_j, y_j]$ are not parallel in F^2 . In a field of order q, we know that there are q+1 unique parallel classes of nonzero vectors in F^2 . Let the elements of F be $0, 1, f_3, f_4, \ldots, f_q$. Take the vectors $[0, 1], [1, 0], [1, 1], [1, f_3], \ldots, [1, f_q]$ as representatives of these parallel classes. For

 $i = 1, \ldots, n$, define $[x_i, y_i]$ to be [0, 1] if $i \in n_1$, [1, 0] if $i \in n_2$, and $[1, f_j]$ if $i \in n_j$ and $j \ge 3$. The vectors $\mathbf{x} = [x_i]$ and $\mathbf{y} = [y_i]$ satisfy $\mathbf{x}\mathbf{y}^T - \mathbf{y}\mathbf{x}^T \in \mathcal{S}^-(F, G)$, so $\mathrm{mr}^-(F, G) = 2$.

 $(1\Longrightarrow 2)$ Assume that G is connected and $\operatorname{mr}^{-}(F,G) = 2$. Then we can find $\mathbf{x}, \mathbf{y} \in F^{n}$ so that $\mathbf{xy}^{T} - \mathbf{yx}^{T} \in \mathcal{S}^{-}(F,G)$. As above, $(\mathbf{xy}^{T} - \mathbf{yx}^{T})_{ij} = x_{i}y_{j} - y_{i}x_{j} = 0$ if and only if vectors $[x_{i}, y_{i}]$ and $[x_{j}, y_{j}]$ are nonzero and parallel or one of them is the zero vector. Note that $[x_{i}, y_{i}] \neq [0, 0]$ for all i because otherwise G would be disconnected. Partition the vertices into sets $V_{1}, V_{2}, \ldots, V_{t}$, where vertices i and j are in the same set if and only if the vectors $[x_{i}, y_{i}]$ and $[x_{j}, y_{j}]$ are parallel. Since there are only q + 1 parallel equivalence classes of nonzero vectors in F^{2} , we have $2 \leq t \leq q + 1$. Thus G will be a complete multipartite graph with partite sets $V_{1}, V_{2}, \ldots, V_{t}$ of orders $n_{1}, n_{2}, \ldots, n_{t}$, respectively, with $2 \leq t \leq q + 1$.

Remark 2.4. If $|G| \le q+1$, then (2) and (1) above are also equivalent to the fact that G does not contain a P_4 or a paw as an induced subgraph.

Theorem 2.5. For a graph G and a field F, $MR^{-}(F,G) = 2 \operatorname{match}(G)$, and every even rank between $\operatorname{mr}^{-}(F,G)$ and $MR^{-}(F,G)$ is realized by a matrix in $\mathcal{S}^{-}(F,G)$.

Proof. Let $A \in S^{-}(F,G)$, |G| = n, and match(G) = m. Then for any $\ell \times \ell$ principal submatrix B of $A, B \in S^{-}(H)$ for an induced subgraph H of G. If $\ell > 2m$, then H has no perfect matching. Hence we have pf(B) = 0, which implies that det B = 0. This holds for all $\ell > 2m$, whence rank $A \leq 2m$ by Theorem 1.1. Thus $MR^{-}(F,G) \leq 2 \operatorname{match}(G)$.

Renumber the vertices in the graph G (if necessary) such that the independent edges in a maximum matching are $\{\{1,2\},\{3,4\},\ldots,\{2m-1,2m\}\}$. If X_G is the formal skew adjacency matrix of G, then pf $(X_G[\{1,\ldots,2m\}])$ is not the zero polynomial. Construct the matrix $B = [b_{ij}]$ over the field F by choosing values $b_{ij} \in F$ for the variables x_{ij} that make pf $(B[\{1,\ldots,2m\}]) \neq 0$; it is obvious we can make such a choice for an infinite field, and Proposition 6.1 in the Appendix shows we can make such a choice for a finite field. Thus det $(B[\{1,\ldots,2m\}]) \neq 0$, and we can complete $B \in S^-(F, G)$ by choosing any nonzero values for the remaining nonzero entries. Since $B \in S^-(F, G)$ and rank $B \geq 2m$, MR⁻(F, G) = 2m.

We can go from any matrix $B \in S^-(F, G)$ to any other matrix $A \in S^-(F, G)$ by adding (one at a time) the matrix $S_{ij}, j > i$ such that $S_{ij}[\{i, j\}] = \begin{bmatrix} 0 & a_{ij} - b_{ij} \\ b_{ij} - a_{ij} & 0 \end{bmatrix}$ and all other entries are zero. Since rank $S_{ij} = 2$, we must pass through every even rank in the transition from a maximum rank matrix B to a minimum rank matrix A.

Theorem 2.6. For a graph G and a field F that has at least 5 elements, $mr^{-}(F,G) = |G| = MR^{-}(F,G)$ if and only if G has a unique perfect matching.

Proof. If G has a unique perfect matching, then as noted in Observation 1.7, for any field F, $mr^{-}(F,G) = |G|$.

Conversely, suppose $\operatorname{mr}^{-}(F,G) = |G|$. Clearly, this implies that $\operatorname{mr}^{-}(F,G) = \operatorname{MR}^{-}(F,G)$. Since every $A \in \mathcal{S}^{-}(F,G)$ has full rank, det $A \neq 0$ for all $A \in \mathcal{S}^{-}(F,G)$. Applying Theorem 1.4 we determine that $\operatorname{pf}(A) \neq 0$ for $A \in \mathcal{S}^{-}(F,G)$. Since the nonzero terms of the pfaffian correspond to perfect matchings of G, G has at least one perfect matching.

Now assume F has at least 5 elements (a field of characteristic not 2 that has at least 4 elements has at least 5). It remains to show that the perfect matching is unique. Suppose that G contains at least two perfect matchings. If so, we show that there exists some $B = [b_{ij}] \in S^-(F,G)$ with pf(B) = 0. Let X_G be the formal skew adjacency matrix of G, and let the $pf(X_G) = p(y_1, \ldots, y_k)$, where y_i are the entries of X_G that appear in the pfaffian. Since there are at least two nonzero terms, by Proposition 6.3 in the Appendix, we can choose nonzero values b_1, \ldots, b_k for y_1, \ldots, y_k so that $p(b_1, \ldots b_k) = 0$. By setting the entry corresponding to y_j equal to $b_j, j = 1, \ldots, k$, and all other nonzero entries to any nonzero value, we can find a $B \in S^-(F, G)$ having pf(B) = 0, which is a contradiction.

Corollary 2.7. If G has a matching with k edges and this is the only perfect matching for the subgraph induced by the 2k vertices in the matching, then over any field F, $mr^{-}(F,G) \ge 2k$.

Theorem 2.8. Let T be a tree and let F be a field. Then $mr^{-}(F,T) = 2 \operatorname{match}(T) = MR^{-}(F,T)$.

Proof. By Theorem 2.5, $\operatorname{mr}^-(F,T) \leq 2 \operatorname{match}(T)$. Let $\{v_1, \ldots, v_k\}$ be the vertices in a maximum matching of a graph G. The induced subgraph $H = G[\{v_1, v_2, \ldots, v_k\}]$, is a forest that has a perfect matching. This perfect matching is unique, because if we choose any leaf of H, it has only one edge, so it must be matched with its only neighbor. Excluding these two vertices, we are left with a forest which still has a perfect matching and still has a leaf. We continue this procedure until each vertex in H is matched. Thus $\operatorname{mr}^-(F,T) \geq 2 \operatorname{match}(T)$

Let M be a matching obtained by starting with a leaf, matching it, removing the match from the graph, and continuing with this procedure. By Theorem 1.6, the only way to have a matching of order greater than |M| would be to have an M-augmenting path. Since we started with an edge that is a leaf of the tree, it is impossible to find an M-augmenting path. Therefore, this matching is a maximum matching of T. Thus we have the following observation.

Observation 2.9. We can determine match(T) by starting with a vertex of degree 1, matching it, removing the match from the graph, and continuing in this manner.

In the proof of Theorem 2.8 it was shown that a tree T has an induced subgraph H such that $mr^{-}(F,T) = |H| = mr^{-}(F,H)$ (and H has a unique perfect matching). This need not be true in general, as the next example shows.

Example 2.10. Let P be the Petersen graph (shown in Figure 3).



Figure 3: The Petersen graph P

Any matrix $A \in \mathcal{S}^{-}(F, P)$ can be put in the form

	Γ0	a	0	0	b	1	0	0	0	[0
A =	-a	0	c	0	0	0	1	0	0	0
	0	-c	0	d	0	0	0	1	0	0
	0	0	-d	0	e	0	0	0	1	0
	-b	0	0	-e	0	0	0	0	0	1
	-1	0	0	0	0	0	0	g	h	0
	0	-1	0	0	0	0	0	0	s	q
	0	0	-1	0	0	-g	0	0	0	r
	0	0	0	-1	0	-h	-s	0	0	0
	0	0	0	0	-1	0	-q	-r	0	0

by use of a diagonal congruence. It is easy to verify by computation that every induced subgraph of order 8 has two perfect matchings. However, $mr^{-}(F, P) = 8$, because any choice of values of the variables makes at least one order 8 principal submatrix nonsingular. Specifically,

 $\det(A[\{1,2,3,4,5,6,7,8\}]) = (e - bdg)^2 \tag{1}$

$$\det(A[\{1,2,3,4,5,6,9,10\}]) = (c - adh)^2$$
(2)

$$\det(A[\{1, 2, 3, 4, 5, 6, 8, 9\}]) = (bcg + aeh)^2$$
(3)

Substituting e = bdg and c = adh into Equation (3) results in

$$\det(A[\{1, 2, 3, 4, 5, 6, 8, 9\}]) = 4a^2b^2d^2g^2h^2 \neq 0.$$

3 Results derived using minimum rank techniques

In this section, we examine connections between the classical minimum rank (using symmetric matrices) and minimum skew rank. Minimum rank and minimum skew rank are noncomparable, but minimum Hermitian rank is a lower bound on minimum skew rank (over the real numbers).

Example 3.1. The minimum skew rank of a graph can be greater than the minimum rank of the graph: $mr(F, K_2) = 1 < 2 = mr^-(F, K_2)$. The minimum skew rank can also be less than the minimum rank: $mr^-(F, K_{3,3,3}) = 2 < 3 = mr(F, K_{3,3,3})$ [5] (as always, char $F \neq 2$).

Proposition 3.2. $\operatorname{hmr}(G) \leq \operatorname{mr}^{-}(\mathbb{R}, G).$

Proof. If $A \in \mathcal{S}^{-}(\mathbb{R}, G)$ then $iA \in \mathcal{H}(G)$ and $\operatorname{rank}(iA) = \operatorname{rank} A$, so $\operatorname{hmr}(G) \leq \operatorname{mr}^{-}(G)$.

Proposition 3.3. Let $G = \bigcup_{i=1}^{h} G_i$. If F is an infinite field or if G_i and G_j have no edges in common for all $i \neq j$, then $\operatorname{mr}^-(F, G) \leq \sum_{i=1}^{h} \operatorname{mr}^-(F, G_i)$.

Proof. A skew-symmetric matrix $A \in F^{n \times n}$ of rank at most $\sum_{i=1}^{h} \operatorname{mr}^{-}(F, G_i)$ having $\mathcal{G}(A) = G$ can be constructed by choosing (for each $i = 1, \ldots, h$) a matrix A_i that realizes $\operatorname{mr}^{-}(G_i)$, embedding A_i in a matrix $\widetilde{A_i}$ of size |G|, choosing $a_i \in F$ such that no cancellation of nonzero entries occurs, and letting $A = \sum_{i=1}^{h} a_i \widetilde{A_i}$.

3.1 Zero forcing number

An upper bound for M(F,G), which yields an associated lower bound for mr(F,G), is the zero forcing number Z(G) introduced in [1]. The zero forcing number is a useful tool for determining the minimum rank of structured families of graphs and small graphs, and is motivated by simple observations about null vectors of matrices. In this subsection we extend these ideas to minimum skew rank.

Definition 3.4. Let G = (V, E) be a graph.

- A subset $Z \subset V$ defines an *initial coloring* by coloring all vertices in Z black and all the vertices not in Z white.
- The skew color change rule says: If a vertex $v \in V$ has exactly one white neighbor, w, change the color of w to black. In this case we say that v forces w.
- The skew derived set of an initial coloring Z is the result of applying the skew color change rule until no more changes are possible.
- A skew zero forcing set is a subset $Z \subseteq V$ such that the skew derived set of Z is V.
- The skew zero forcing number, $Z^{-}(G)$, is the minimum size of a skew zero forcing set.

If $\mathbf{x} = [x_k]$ is a nonzero null vector of the skew-symmetric matrix A whose graph is G, and i is a vertex of G, then either i has no neighbors j such that x_j is nonzero or at least two neighbors j such that x_j is nonzero. If A is a skew-symmetric matrix of nullity k, then for every set Z of cardinality k - 1, there is a nonzero null vector \mathbf{x} of A with $x_j = 0$ for all $j \in Z$. Thus if Z is a skew zero forcing of G, then for each matrix in $S^-(F, G)$ the only null vector with 0's in positions indexed by Z is the zero vector. These ideas provide the proof of the next proposition, just as analogous statements about symmetric matrices provide the proof of Proposition 2.4 in [1].

Proposition 3.5. For any graph G and any field F, $M^-(F,G) \leq Z^-(G)$ and $mr^-(F,G) \geq |G| - Z^-(G)$.

Proposition 3.6. For any graph G, $Z^{-}(G) \leq Z(G)$. If mr(F,G) = |G| - Z(G) for a field F, then $mr^{-}(F,G) \geq mr(F,G)$.

Proof. Let Z be an optimal zero forcing set for the graph G, i.e, |Z| = Z(G). The set Z is also a skew zero forcing set for G, although Z may not be an optimal skew zero forcing set. Thus $Z^{-}(G) \leq |Z| = Z(G)$.

Therefore, if mr(F,G) = |G| - Z(G), it follows by Proposition 3.5 that $mr^{-}(F,G) \ge |G| - Z^{-}(G) \ge |G| - Z(G) = mr(F,G)$.

See [1] for a list of graphs G for which it is known that $mr(\mathbb{R}, G) = |G| - Z(G)$.

The Cartesian product of two graphs G and H, denoted $G \Box H$, is the graph with vertex set $V_G \times V_H$ such that (u, v) is adjacent to (u', v') if and only if (1) u = u' and $\{v, v'\} \in E_H$, or (2) v = v' and $\{u, u'\} \in E_G$.

Corollary 3.7. For any field F and any graph G, $\operatorname{mr}^-(F, G \Box P_t) \ge (t-1)|G|$. If t is even and |G| is odd, then $\operatorname{mr}^-(F, G \Box P_t) \ge (t-1)|G| + 1$.

Proof. All the vertices in a pendant copy of G are a zero forcing set, and minimum skew rank must be even.

3.2 Cut-vertex reduction

The rank-spread of a graph G was defined in [4] and used to establish cut-vertex reduction, whereby the computation of the minimum rank of a graph with a cut-vertex could be reduced to computing the minimum rank of certain proper subgraphs. In this subsection we extend these ideas to minimum skew rank.

The *skew-rank-spread* of G at vertex v over a field F is defined to be

$$\mathbf{r}_{v}^{-}(F,G) = \mathbf{mr}^{-}(F,G) - \mathbf{mr}^{-}(F,G-v).$$

Clearly for any vertex v of G, $r_v^-(F,G)$ is either 0 or 2.

Lemma 3.8. Let $G = (V = \{v_1, \ldots, v_n, v\}, E)$ be a graph. Over a field F, $\mathbf{r}_v^-(F, G) = 0$ if and only if there exist an optimal matrix $A' \in F^{n \times n}$ for G - v and a vector $\mathbf{b} = [b_i] \in \operatorname{range} A'$ such that $b_i \neq 0$ if and only if v is adjacent to v_i , and $\mathbf{r}_v^-(F, G) = 2$ otherwise.

Proof. Suppose there exists an optimal matrix $A' \in F^{n \times n}$ for G - v and a vector $\mathbf{b} = [b_i] \in \text{range } A'$ such that $b_i \neq 0$ if and only if v is adjacent to v_i . Then

$$A = \begin{bmatrix} A' & \mathbf{b} \\ -\mathbf{b}^T & 0 \end{bmatrix} \in \mathcal{S}^-(F, G).$$
(4)

Since $\mathbf{b} \in \operatorname{range} A'$, there exists $\mathbf{x} \in F^n$ such that $\mathbf{b} = A'\mathbf{x}$. Since $\mathbf{x}^T A'\mathbf{x} = (\mathbf{x}^T A'\mathbf{x})^T = -\mathbf{x}^T A'\mathbf{x}$, $\mathbf{x}^T A'\mathbf{x} = 0$ and rank $A = \operatorname{rank} A'$. Thus $\mathbf{r}_v^-(F, G) = 0$. Conversely, if $\mathbf{r}_v^-(G) = 0$, any optimal matrix A will have the form (4) with rank $A' = \operatorname{mr}^-(F, G - v)$ and $\mathbf{b} \in \operatorname{range} A'$. Since $0 \leq \mathbf{r}_v^-(F, G) \leq 2$ and the rank of a skew matrix is even, $\mathbf{r}_v^-(F, G) = 2$ if and only if $\mathbf{r}_v^-(F, G) \neq 0$.

Theorem 3.9. [8] Let v be a cut-vertex of G. For i = 1, ..., h, let $W_i \subseteq V(G)$ be the vertices of the *i*th component of G - v and let G_i be the subgraph induced by $\{v\} \cup W_i$. Then over a field F,

$$r_v^-(F,G) = \max_{i=1,\dots,h} r_v^-(F,G_i), \text{ and }$$

$$\mathrm{mr}^{-}(F,G) = \begin{cases} \sum_{1}^{h} \mathrm{mr}^{-}(F,G_{i}-v) & \text{if } \mathrm{r}_{v}^{-}(F,G_{i}) = 0 \text{ for all } i = 1, \dots, h\\ \sum_{1}^{h} \mathrm{mr}^{-}(F,G_{i}-v) + 2 & \text{if } \mathrm{r}_{v}^{-}(F,G_{i}) = 2 \text{ for some } i, \ 1 \le i \le h \end{cases}$$

Proof. In both cases, $\sum_{1}^{h} \operatorname{mr}^{-}(F, G_{i} - v) = \operatorname{mr}^{-}(F, G - v) \leq \operatorname{mr}^{-}(F, G)$. First assume that $r_{v}^{-}(F, G_{i}) = 0$ for all $i = 1, \ldots, h$. Then $\sum_{1}^{h} \operatorname{mr}^{-}(F, G_{i} - v) = \sum_{1}^{h} \operatorname{mr}^{-}(F, G_{i})$. Since v is a cut-vertex, there are no overlapping edges, and by Proposition 3.3, $\operatorname{mr}^{-}(F, G) \leq \sum_{1}^{h} \operatorname{mr}^{-}(F, G_{i})$. Thus $\operatorname{mr}^{-}(F, G) = \sum_{1}^{h} \operatorname{mr}^{-}(F, G_{i} - v)$.

Now assume $\mathbf{r}_v^-(F, G_k) = 2$ for some k. Then by Lemma 3.8, for every matrix $A^{(k)}$ that is optimal for $G_k - v$ and vector $\mathbf{b}^{(k)}$ having a nonzero pattern reflecting the adjacencies of v within G_k , $\mathbf{b}^{(k)} \notin$ range $A^{(k)}$. Thus for every matrix A' that is optimal for G - v and vector \mathbf{b} having a nonzero pattern reflecting the adjacencies of v within G, $\mathbf{b} \notin$ range A' because A' is block-diagonal. Thus by Lemma 3.8, $\mathbf{r}_v^-(F, G) = 2$.

Proposition 3.10. If F is an infinite field, G' is connected, $|G| \ge 2$, and $G = G' \lor K_1$, then $\operatorname{mr}^-(F,G) = \operatorname{mr}^-(F,G')$.

Proof. Let A' be an optimal matrix for G', and let $V(K_1) = \{v\}$. Since every row of A' has a nonzero entry, there exists $\mathbf{b} \in \operatorname{range} A'$ such that every entry of \mathbf{b} is nonzero. Then by Lemma 3.8, $\mathbf{r}_v^-(G) = 0$.

4 Computation of minimum skew rank of selected graphs

In this section we apply the results in the preceding sections to determine the minimum skew rank of some additional families of graphs. The minimum (symmetric) rank of these graphs is known and listed in the AIM minimum rank graph catalog [2]. We begin by defining several families of graphs.

The wheel on *n* vertices, denoted by W_n , is constructed by adding a new vertex adjacent to all vertices of the cycle C_{n-1} . The sth hypercube, Q_s , is defined inductively by $Q_1 = K_2$ and $Q_{s+1} = Q_s \Box K_2$. Clearly $|Q_s| = 2^s$. The *m*, *k*-pineapple (with $m \ge 3, k \ge 2$) is $P_{m,k} = K_m \cup K_{1,k}$ such that $K_m \cap K_{1,k}$ is the vertex of $K_{1,k}$ of degree k; $P_{5,3}$ is shown in Figure 4.



Figure 4: The pineapple $P_{5,3}$

The sth half-graph, denoted H_s , is constructed from (disjoint) graphs K_s and $\overline{K_s}$, having vertices $u_1, \ldots, u_s, v_{s+1}, \ldots, v_{2s}$, respectively, by adding all edges $\{u_i, v_j\}$ such that $i + j \leq 2s + 1$. Figure 5 shows H_3 , with the vertices of the K_3 being colored black and the vertices of the $\overline{K_3}$ colored grey. Note that half graph H_s is the graph on 2s vertices with the largest number of edges among graphs G such that G has a unique perfect matching (in Figure 5, the three heavy lines are the unique perfect matching of H_3).



Figure 5: The 3rd half-graph H_3

The *necklace* with s diamonds, denoted N_s , is a 3-regular graph on 4s vertices that can be constructed from a 3s-cycle by appending s extra vertices, with each "extra" vertex adjacent to 3 sequential cycle vertices; N_3 is shown in Figure 6 (the coloring of the vertices is explained in the proof of Proposition 4.4).



Figure 6: The necklace N_3

The corona of G with H, denoted $G \circ H$, is the graph of order |G||H| + |G| obtained by taking one copy of G and |G| copies of H, and joining all the vertices in the *i*th copy of H to the *i*th vertex of G.

For many of the graphs we discuss, the minimum skew rank is the same over all fields (of characteristic not 2), but as we saw in Example 2.2, the minimum skew rank can differ for finite fields, and it seems plausible that like minimum (symmetric) rank, minimum skew rank can differ even over fields of characteristic zero, although we do not have an example of such a graph.

Proposition 4.1. Let F be a field.

1.
$$\operatorname{mr}^{-}(F, P_n) = \begin{cases} n & \text{if } n \text{ is even} \\ n-1 & \text{if } n \text{ is odd} \end{cases}$$

2. $\operatorname{mr}^{-}(F, P_{m,k}) = 4 \ (m \ge 3, k \ge 2).$
3. $\operatorname{mr}^{-}(F, H_s) = 2s = |H_s|.$
4. $\operatorname{mr}^{-}(F, G \circ K_1) = 2|G| = |G \circ K_1|.$

Proof.

- 1. This is an immediate consequence of Theorem 2.8.
- 2. $P_{m,k} = K_m \cup K_{1,k}$, so by Proposition 3.3, $\operatorname{mr}^-(F, P_{m,k}) \leq \operatorname{mr}^-(F, K_m) + \operatorname{mr}^-(F, K_{1,k}) = 4$. Since $P_{m,k}$ contains the paw as an induced subgraph, $\operatorname{mr}^-(P_{m,k}) \geq 4$.
- 3. H_s has a unique perfect matching, so Observation 1.7 applies.
- 4. $G \circ K_1$ has a unique perfect matching, so again Observation 1.7 applies.

Proposition 4.2. Over any field F, $mr^{-}(F, C_n) = \begin{cases} n-1 & \text{if } n \text{ is odd} \\ n-2 & \text{if } n \text{ is even} \end{cases}$.

Proof. Note that C_n has an induced P_{n-1} , so $\operatorname{mr}^-(F, C_n)$ is at least the stated rank. Define $A_n = [a_{ij}] \in \mathcal{S}^-(F, C_n)$ by $a_{i,i+1} = 1, a_{i+1,i} = -1, i = 1, \ldots, n-1, a_{n,1} = 1, a_{1,n} = -1$ and all other entries are zero. Since $[1, 1, \ldots, 1, 1]^T \in \ker A$, and if n is even, $[1, -1, \ldots, 1, -1]^T \in \ker A$, rank A realizes the stated minimum rank.

Since $W_n = C_{n-1} \vee K_1$, by Proposition 3.10 we have the following corollary.

Corollary 4.3. Over an infinite field F, $mr^-(F, W_n) = \begin{cases} n-2 & \text{if } n \text{ is even} \\ n-3 & \text{if } n \text{ is odd} \end{cases}$.

Proposition 4.4. Over any field F with at least 5 elements, $mr^{-}(F, N_s) = 4s - 2$.

Proof. Since N_s has 4s vertices and more than one perfect matching (because it contains a 4s-cycle), by Theorem 2.6, mr⁻(N_s) $\leq 4s - 2$. The deletion of two vertices from the 3s-cycle that are the ends of consecutive diamonds leaves an induced subgraph with a unique perfect matching (in Figure 6, if the two grey vertices are deleted, then the heavy edges are the unique perfect matching), so mr⁻(N_s) $\geq 4s - 2$.

Proposition 4.5. Over any field F, for $s \ge 2$, $\operatorname{mr}^-(F, C_t \circ K_s) = \begin{cases} 3t-1 & \text{if } t \text{ is odd} \\ 3t-2 & \text{if } t \text{ is even} \end{cases}$.

Proof. Since $C_t \circ K_s$ can be covered by t copies of K_{s+1} and one C_t , intersecting only at cycle vertices, by Proposition 3.3, $mr^-(F, C_t \circ K_s) \leq 2t + (t-1)$ if t is odd, or t-2 if t is even) = 3t - 1 if t is odd, or 3t - 2 if t is even.

Let Z be the set of vertices consisting of all but 2 of the vertices in each K_s and two consecutive vertices on the cycle. Note that |Z| = t(s-2) + 2. Then Z is a zero forcing set for $C_t \circ K_s$, so $ts + t - (t(s-2) + 2) = 3t - 2 \le \mathrm{mr}^-(C_t \circ K_s)$. So if t is even, $\mathrm{mr}^-(C_t \circ K_s) = 3t - 2$. If t is odd, 3t - 2 is odd, so $\mathrm{mr}^-(C_t \circ K_s) = 3t - 1$.

Proposition 4.6. Over a field F such that the characteristic of F is 0, or $|F| \ge 6$, $mr^{-}(F, Q_s) = 2^{s-1}$ for $s \ge 2$.

Proof. Over any field, $mr^{-}(F, Q_s) \ge 2^{s-1}$ by Corollary 3.7.

Let F be as prescribed. As noted in [7, Theorem 3.14], there are nonzero scalars α, β in F such that $\alpha^2 + \beta^2 = 1$. We define the matrices L_s as follows:

$$L_1 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \text{ and } L_s = \begin{bmatrix} \alpha L_{s-1} & \beta I \\ -\beta I & -\alpha L_{s-1} \end{bmatrix}.$$

Each $L_s \in F^{2^s \times 2^s}$ is a skew-symmetric matrix. We show by induction that $L_s^2 = -I_{2^s}$. This is clearly true for s = 1. Next, we assume $L_{s-1}^2 = -I_{2^{s-1}}$, so

$$L_{s}^{2} = \begin{bmatrix} \alpha L_{s-1} & \beta I \\ -\beta I & -\alpha L_{s-1} \end{bmatrix}^{2} = \begin{bmatrix} \alpha^{2} L_{s-1}^{2} - \beta^{2} I & 0 \\ 0 & -\beta^{2} I + \alpha^{2} L_{s-1}^{2} \end{bmatrix} = \begin{bmatrix} -I & 0 \\ 0 & -I \end{bmatrix}$$

Define

$$H_s = \begin{bmatrix} L_{s-1} & I \\ -I & L_{s-1} \end{bmatrix}.$$

Each $H_s \in F^{2^s \times 2^s}$ is a skew-symmetric matrix such that $H_s \in \mathcal{S}^-(Q_s)$. Since

$$\begin{bmatrix} I & 0 \\ -L_{s-1} & I \end{bmatrix} \begin{bmatrix} L_{s-1} & I \\ -I & L_{s-1} \end{bmatrix} = \begin{bmatrix} L_{s-1} & I \\ 0 & 0 \end{bmatrix},$$

rank $H_s = 2^{s-1}$. Therefore, $\operatorname{mr}^-(F, Q_s) \le 2^{s-1}$ for $s \ge 2$.

4.1 Minimum skew rank over the real numbers

In this subsection we apply techniques that are specific to the real numbers.

A standard technique for establishing the minimum (symmetric) rank of a Cartesian product $G\Box H$ is to use a Kronecker product construction to produce a matrix in $\mathcal{S}(G\Box H)$ (cf. [1]) (and use the zero forcing number to bound the minimum rank from below). We adapt this method to minimum skew rank.

If A is an $s \times s$ real matrix and B is a $t \times t$ real matrix, then $A \otimes B$ is the $s \times s$ block matrix whose ijth block is the $t \times t$ matrix $a_{ij}B$. Note that $(A \otimes B)^T = A^T \otimes B^T$, so if one of A, B is symmetric and the other is skew-symmetric, $A \otimes B$ is skew-symmetric. Let G be a graph on s vertices, let H be a graph on t vertices, let $A \in S^-(G)$ and $B \in S^-(H)$. Then $A \otimes I_t + I_s \otimes B \in S^-(G \square H)$ (cf. [10, 9.7]). If **x** is an eigenvector of A for eigenvalue λ and **y** is an eigenvector of B for eigenvalue μ , then $\mathbf{x} \otimes \mathbf{y}$ is an eigenvector of $A \otimes I_t + I_s \otimes B$ for eigenvalue $\lambda + \mu$.

Lemma 4.7. Let $A \in \mathbb{R}^{n \times n}$ be skew-symmetric and let the distinct eigenvalues of A be $\lambda_1, \ldots, \lambda_k$ with multiplicities m_1, \ldots, m_k . Then $\operatorname{rank}(A \otimes I_n - I_n \otimes A) \leq n^2 - \sum_{i=1}^k m_i^2$.

Proof. Since A is skew-symmetric, over \mathbb{C} there exist independent eigenvectors $\mathbf{x}_{j}^{(i)}, j = 1, \ldots, m_{i}$ for λ_{i} , and thus independent null vectors $\mathbf{x}_{j}^{(i)} \otimes \mathbf{x}_{\ell}^{(i)}, 1 \leq j, \ell \leq m_{i}, 1 \leq i \leq k$. Thus viewing $A \in \mathbb{C}^{n \times n}$, rank $A \leq n^{2} - \sum_{i=1}^{k} m_{i}^{2}$, and viewing A as a real matrix does not increase its rank. \Box

Proposition 4.8. $\operatorname{mr}^{-}(\mathbb{R}, P_s \Box P_s) = s^2 - s = \operatorname{mr}(\mathbb{R}, P_s \Box P_s).$

Proof. Since $Z(P_s \Box P_s) = M(\mathbb{R}, P_s \Box P_s) = s$ [1], by Proposition 3.6, $s^2 - s = mr(\mathbb{R}, P_s \Box P_s) \le mr^-(\mathbb{R}, P_s \Box P_s)$. But by Lemma 4.7, for any $A \in S^-(\mathbb{R}, P_s)$, rank $(A \otimes I_n - I_n \otimes A) \le s^2 - s$ and $A \otimes I_n - I_n \otimes A \in S^-(\mathbb{R}, P_s \Box P_s)$, so $mr^-(\mathbb{R}, P_s \Box P_s) \le s^2 - s$.

Lemma 4.9. There exists $A \in S^{-}(K_n)$ such that $\operatorname{mult}_A(i) = \operatorname{mult}_A(-i) = \lfloor \frac{n}{2} \rfloor$ (and zero is an eigenvalue of multiplicity one if n is odd).

Proof. Let $B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \oplus \cdots \oplus \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ if *n* is even and $B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \oplus \cdots \oplus \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \oplus [0]$ if *n* is odd. Choose a real orthogonal matrix *U* such that UBU^* has all off-diagonal entries nonzero. \Box

Proposition 4.10.

$$mr^{-}(K_{s}\Box P_{t}) = \begin{cases} st - s + 1 & \text{if s is odd and t is even;} \\ st - s & \text{otherwise.} \end{cases}$$

Proof. $s = Z(K_s \Box P_t) \leq Z^-(K_s \Box P_t)$ (the equality was established in [1]), so $st - s \leq mr^-(K_s \Box P_t)$. In the case s is odd and t is even, st - s is odd, so $st - s + 1 \leq mr^-(K_s \Box P_t)$.

Construct $A_s \in \mathcal{S}^-(K_s)$ such that $\operatorname{mult}_A(i) = \operatorname{mult}_A(-i) = \lfloor \frac{s}{2} \rfloor$ (and 0 as an eigenvalue of multiplicity one if s is odd). By scalar multiplication we can construct $B_t \in \mathcal{S}^-(P_t)$ having eigenvalues $\pm i$, and also 0 if t is odd. Then $\operatorname{mult}_{A_s \otimes I_t + I_s \otimes B_t}(0) = s$, except if s is odd and t is even, $\operatorname{mult}_{A_s \otimes I_t + I_s \otimes B_t}(0) = s - 1$. Thus $st - s \geq \operatorname{mr}^-(K_s \Box P_t)$, except if s is odd and t is even, $st - s + 1 \geq \operatorname{mr}^-(K_s \Box P_t)$.

5 Open questions

In this section we list some open questions about minimum skew rank. We assume throughout this section that the field F is infinite, because the answers differ for finite fields.

Note that for n even, [12] completely characterizes those G for which there is a unique perfect matching, hence by Theorem 2.6, the graphs for which $mr^{-}(F,G)$ is as large as possible. It is natural to ask the same question for n odd, namely:

Question 5.1. Characterize G such that $mr^{-}(F,G) = |G| - 1$.

Examples of graphs with this property include any graph G with a vertex v such that G - v has a unique perfect matching. To date these are the only known examples (over an infinite field). Example 2.2 shows $mr^{-}(\mathbb{Z}_3, K_5) = |K_5| - 1$, despite the fact that $K_5 - v = K_4$ does not have a unique perfect matching for any vertex v.

Question 5.2. Characterize the graphs G such that $mr^{-}(F,G) = 4$.

Since 4 is the second smallest possible minimum skew rank of a graph that has an edge, Question 5.2 is related to the interesting and important results characterizing mr(G) = 2 (for symmetric matrices) in [5]. Again, Example 2.2 shows that the answer can be different over a finite field.

Question 5.3. Characterize G such that $mr^{-}(F,G) = MR^{-}(F,G)$.

Again, Example 2.2 shows that the answer can be different over a finite field. A graph G satisfying $mr^{-}(F,G) = MR^{-}(F,G)$ is said to have fixed rank (over F), since rank A is constant for $A \in \mathcal{S}^{-}(F,G)$.

6 Appendix: Polynomials over finite fields

In this appendix we establish some results about polynomials over finite fields that are needed for the proofs given in Section 2. These results may be known, but we don't have a reference.

Proposition 6.1. Let F be a field with $q \ge 3$ elements, and let $p(x_1, x_2, \ldots, x_m)$ be a nonzero homogeneous polynomial in $F[x_1, \ldots, x_m]$ of degree d such that each monomial $x_1^{e_1} x_2^{e_2} \cdots x_m^{e^m}$ satisfies $e_k \le 1$ for $k = 1, 2, \ldots, m$. Then there exist $a_1, a_2, \ldots, a_m \in F \setminus \{0\}$ such that $p(a_1, a_2, \ldots, a_m) \ne 0$.

Proof. The proof is by induction on m. If m = 1, p has the form cx_1 or c for some nonzero c, and we may simply take $x_1 = 1$.

Assume $m \geq 2$ and proceed by induction. Write

$$p(x_1, x_2, \dots, x_m) = x_m r(x_1, \dots, x_{m-1}) + s(x_1, \dots, x_{m-1})$$

for some homogeneous polynomials r and s in $F[x_1, \ldots, x_{m-1}]$. If s is not the zero polynomial, then s is homogeneous of degree d and by the inductive assumption, there exist nonzero a_1, \ldots, a_{m-1} such that $s(a_1, \ldots, a_{m-1}) \neq 0$. If $r(a_1, a_2, \ldots, a_{m-1}) = 0$, then $p(a_1, \ldots, a_{m-1}, 1) \neq 0$. Otherwise,

$$p(a_1,\ldots,a_{m-1},a_m)\neq 0$$

for each a_m other than $-\frac{s(a_1,...,a_{m-1})}{r(a_1,...,a_{m-1})}$. Since F has at least two nonzero is elements, there is such an a_m .

Next consider the case that s is the zero polynomial. Since p is not the zero polynomial, r is not the zero polynomial, and hence is a nonzero homogeneous polynomial in m-1 variables. By induction there exist $a_1, \ldots, a_{m-1} \in F \setminus \{0\}$ with $r(a_1, a_2, \ldots, a_{m-1}) \neq 0$, and hence $p(a_1, a_2, \ldots, a_{m-1}, 1) \neq 0$.

Lemma 6.2. Let F be a field with $q \ge 4$ elements, and let $t(x_1, x_2, \ldots, x_m)$ be a nonzero homogeneous polynomial in $F[x_1, \ldots, x_m]$ of degree d such that each monomial $x_1^{e_1} x_2^{e_2} \cdots x_m^{e^m}$ satisfies $e_k \le 2$ for $k = 1, 2, \ldots, m$. Then there exist $a_1, \ldots, a_m \in F \setminus \{0\}$ such that $t(a_1, \ldots, a_m) \ne 0$.

Proof. By induction on m. If m = 1, then $t(x_m)$ is cx_m^2 , cx_m or c for some nonzero c, and we may take $x_m = 1$.

Assume $m \ge 2$ and proceed by induction. Write

$$t(x_1,\ldots,x_m) = x_m^2 j(x_1,x_2,\ldots,x_{m-1}) + x_m k(x_1,\ldots,x_{m-1}) + \ell(x_1,\ldots,x_{m-1}).$$

For $a_1, \ldots, a_{m-1} \in F \setminus \{0\}$,

$$t(a_1,\ldots,a_{m-1},x_m) = x_m^2 j(a_1,a_2,\ldots,a_{m-1}) + x_m k(a_1,\ldots,a_{m-1}) + \ell(a_1,a_2,\ldots,a_{m-1})$$

is a polynomial in $F[x_m]$. If there is an $a_m \in F \setminus \{0\}$ such that $t(a_1, a_2, \ldots, a_{m-1}, x_m)$ evaluated at $x_m = a_m$ is nonzero, then we are done.

Otherwise, for each choice of $a_1, \ldots, a_{m-1} \in F \setminus \{0\}$, each nonzero element of F is a root of $t(a_1, a_2, \ldots, a_{m-1}, x_m)$. We claim that this can't occur. As F has at least 4 elements,

 $t(a_1, a_2, \ldots, a_{m-1}, x_m)$ has at least 3 roots and degree at most two. Thus, $t(a_1, a_2, \ldots, a_{m-1}, x_m)$ is the zero polynomial for each choice of $a_1, \ldots, a_{m-1} \in F \setminus \{0\}$. In particular, each of the homogeneous polynomials, j, k, ℓ vanishes at each choice of $(a_1, a_2, \ldots, a_{m-1})$ with $a_1, \ldots, a_{m-1} \in F \setminus \{0\}$. Hence by induction, each of j, k and ℓ is the zero polynomial, which cannot happen since t is nonzero. \Box

Note that if F is the field with 3 elements, and $p(x, y) = x^2 - y^2$, then p(a, b) = 0 for each choice of $a, b \in F \setminus \{0, 1\}$. So Lemma 6.2 needs $q \ge 4$.

Proposition 6.3. Let F be a field with more than 3 elements, and let $p(x_1, x_2, \ldots, x_m)$ be a nonzero homogeneous polynomial in $F[x_1, \ldots, x_m]$ of degree d such that each monomial $x_1^{e_1} x_2^{e_2} \cdots x_m^{e^m}$ satisfies $e_k \leq 1$ for $k = 1, 2, \ldots, m$. Then either $p(x_1, x_2, \ldots, x_m)$ has exactly one nonzero term or there exist $a_i \in F \setminus \{0\}$ such that $p(a_1, a_2, \ldots, a_m) = 0$.

Proof. Assume that $p(x_1, x_2, \ldots, x_m)$ has at least two nonzero terms. Since p is homogeneous and has at least two nonzero terms, there is an i such that p has one term involving x_i and another term that doesn't involve x_i . Without loss of generality, we may take i = m. Write $p(x_1, \ldots, x_m) = x_m r(x_1, \ldots, x_{m-1}) + s(x_1, \ldots, x_{m-1})$. Since x_m is in some term of $p(x_1, \ldots, x_m)$, r is not the zero polynomial. Since x_m is not in some term of $p(x_1, \ldots, x_m)$, s is not the zero polynomial.

Consider the polynomial $t(x_1, x_2, \ldots, x_{m-1}) = r(x_1, \ldots, x_{m-1})s(x_1, \ldots, x_{m-1})$. Note that t is homogeneous, nonzero, and the exponent of each x_j in each monomial is at most 2. Thus, by Lemma 6.2, there exist nonzero a_1, \ldots, a_{m-1} such that $t(a_1, \ldots, a_{m-1}) \neq 0$. Now observe that

$$p\left(a_1, a_2, \dots, a_{m-1}, \frac{-s(a_1, \dots, a_{m-1})}{r(a_1, \dots, a_{m-1})}\right) = 0$$

and each of $a_1, a_2, ..., a_{m-1}$, and $\frac{-s(a_1, ..., a_{m-1})}{r(a_1, ..., a_{m-1})}$ is nonzero.

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