

## LECTURE 17 (267)

### Forced Oscillations and Resonance.

We consider the mass-spring-dashpot system in the situation when we have the external force  $F_E = F_0 \cos(\omega t)$ . **Undamped Forced Oscillations.** First we consider the case when damping constant  $c = 0$ . Then the motion of our system described by the equation:

$$mx'' + kx = F \cos \omega t \quad (1)$$

We remind that the natural frequency is given by formula  $\omega_0 = \sqrt{\frac{k}{m}}$ . Assume that  $\omega \neq \omega_0$ . In that case the general solution to equation (1) is

$$x(t) = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + \frac{F_0/m}{\omega_0^2 - \omega^2} \cos(\omega t).$$

or

$$x(t) = C \cos(\omega_0 t - \alpha) + \frac{F_0/m}{\omega_0^2 - \omega^2} \cos(\omega t). \quad (2)$$

**Resonance.** We consider the case when

$$\omega = \omega_0.$$

In that case the equation (1) has the form

$$x'' + \omega_0^2 x = \frac{F_0}{m} \cos(\omega_0 t)$$

And the general solution is

$$x(t) = C \cos(\omega_0 t - \alpha) + \frac{F_0}{2m\omega_0} t \sin(\omega_0 t). \quad (3)$$

Damped Forced Oscillations.

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$$mx'' + cx' + kx = F_0 \cos(\omega t) \quad (4)$$

We represent the solution to problem (4) in the form

$$x(t) = x_c(t) + x_p(t)$$

Here  $x_c(t)$  is a solution to the homogeneous equation. We note that  $x_c(t) \rightarrow 0$  as  $t \rightarrow +\infty$ . So  $x_c(t)$  called the **transient solution**.

We introduce two constants  $A$  and  $B$  by formulas

$$A = \frac{(k - m\omega^2)F_0}{(k - m\omega^2)^2 + (c\omega)^2}, \quad B = \frac{c\omega F_0}{(k - m\omega^2)^2 + (c\omega)^2}$$

Then the particular solution has the form

$$x(t) = A \cos(\omega t) + B \sin(\omega t)$$

or

$$x_p(t) = C \cos(\omega t - \alpha), \quad (5)$$

where

$$C = \frac{F_0}{\sqrt{(k - m\omega^2)^2 + (c\omega)^2}}$$

The constant  $C = C(\omega)$  called forced amplitude. The point where function  $C(\omega)$  attain the maximum value is called the particular resonance. If  $c \geq \sqrt{2km}$  then  $C(\omega)$  is steady decreasing function, but if  $c < \sqrt{2km}$  the function  $C$  attain a maximum value for some  $\hat{\omega}$  less than  $\omega_0$ .

$$\alpha = \begin{cases} \tan^{-1} \frac{c\omega}{k - m\omega^2} & \text{if } k > m\omega^2 \\ \pi + \tan^{-1} \frac{c\omega}{k - m\omega^2} & \text{if } k < m\omega^2 \end{cases}$$

**Example 1.** Solve the initial value problem

$$x'' + 100x = 15 \cos 5t + 20 \sin 5t, x(0) = 25, x'(0) = 0.$$

*Solution.* We have  $m = 1, k = 100, \omega_0 = 10$  So the general solution to O.D.E. is

$$x(t) = c_1 \cos(10t) + c_2 \sin(10t) + x_p(t).$$

We look for the function  $x_p(t)$  as the sum of two functions

$$x_p(t) = x_{p,1}(t) + x_{p,2}(t)$$

Here

$$x''_{p,1} + 100x_{p,1} = 15\cos 5t, \quad x''_{p,2} + 100x_{p,2} = 20\sin 5t$$

Using the formula (2) with  $F_0 = 15$  and  $\omega = 10$  we obtain

$$x_{p,1}(t) = \frac{1}{5}\cos 5t.$$

Using the method of undetermined coefficients we are looking for the function  $x_{p,2}(t)$  in the form

$$x_{p,2}(t) = A\cos 5t + B\sin 5t$$

Then

$$x''_{p,2}(t) = -25A\cos 5t - 25B\sin 5t$$

And

$$x''_{p,2} + 100x_{p,2} = 75(A\cos 5t + B\sin 5t) = 20\sin 5t.$$

Therefore  $A = 0, B = \frac{4}{15}$ . The general solution is

$$x(t) = c_1\cos(10t) + c_2\sin(10t) + \frac{1}{5}\cos 5t + \frac{4}{15}\sin(5t).$$

Now we fix the constants  $c_1$  and  $c_2$ .

$$x(0) = 25 = c_1 + \frac{1}{5}$$

Hence  $c_1 = \frac{124}{5}$ . Then

$$x'(0) = 0 = 10c_2 + \frac{4}{3}$$

Hence  $c_2 = -\frac{2}{15}$ . The answer is

$$x(t) = \frac{124}{5}\cos(10t) - \frac{2}{15}\sin(10t) + \frac{1}{5}\cos 5t + \frac{4}{15}\sin(5t).$$

**Example 2.** Find the particular solution  $x_{sp}(t)$  in the form  $x_{sp}(t) = C\cos(\omega t - \alpha)$  for the following ordinary differential equation

$$x'' + 3x' + 5x = -4\cos 5t.$$

**Example 3.** Derive the steady periodic solution of

$$mx'' + cx' + kx = F_0\sin\omega t$$

*Solution.* Using the method of undetermined coefficients we are looking for a solution in the form

$$x_p(t) = A\sin\omega t + B\cos\omega t$$

We need the formulas for the first and the second derivatives of the function  $x_p(t)$ :

$$x_p'(t) = \omega A\cos(\omega t) - \omega B\sin(\omega t), \quad x_p''(t) = -\omega^2(A\sin\omega t + B\cos\omega t).$$

Then

$$-m\omega^2(A\sin\omega t + B\cos\omega t) + c(\omega A\cos(\omega t) - \omega B\sin(\omega t)) + k(A\sin\omega t + B\cos\omega t) = F_0\sin(\omega t).$$

From this equation we obtain

$$(k - m\omega^2)A - c\omega B = F_0, \quad (k - m\omega^2)B + c\omega A = 0.$$

from the second equation we have

$$B = -\frac{c\omega}{k - m\omega^2}A.$$

Hence

$$(k - m\omega^2)A + \frac{(c\omega)^2}{k - m\omega^2}A = F_0$$

and

$$A = \frac{F_0(k - m\omega^2)}{(k - m\omega^2)^2 + (c\omega)^2}.$$

Then

$$B = -\frac{(c\omega)^2}{(k - m\omega^2)^2 + (c\omega)^2}.$$