

TOPICS of MATH 307

Matrices

- Multiplication of matrices
- Special matrices (diagonal, upper(lower) triangular etc.)
- Transpose and inverse of a matrix
- Determinants (definition, calculation, properties)
- Rank of a matrix
- Relationship between rank, determinant and singularity of a matrix

Systems of Linear Algebraic Equations

- Matrix of a system
- Augmented matrix of a system
- Solution of a system
- Gauss-Jordan elimination
 - Elementary row operations
 - Reduced Row Echelon Form
 - Leading ones (pivot columns)
 - Rank of a matrix

Subspaces of \mathbb{R}^n

- Definition (closure by addition and scalar multiplication)
- Linear independence
- Basis and dimension
- Geometric interpretation of 0, 1, 2, 3-dimensional subspaces
- Coordinate systems and transition matrices
- Finding orthonormal bases using Gram-Schmidt method

Linear transformations

- Definition (linearity properties)
- Matrix of a linear transform (how to find it)
- Image and Kernel of linear transform
- Inverse of a linear transform
- Matrices of linear transforms in different bases
- Geometric applications of linear transforms: finding matrices of reflexions, projections, dilations, shears.

Eigenvalues and eigenvectors, diagonalization

- Definitions and calculations of eigenvalues, eigenvectors, eigenspaces
- Matrix and linear transform diagonalization (necessary conditions)

BASIC PROBLEMS Let $L(\mathbf{x}) = A\mathbf{x}$.

Calculate (for each matrix given below)

a) $\det(A)$

b) $rref(A)$, $rank(A)$

c) A^{-1} (or show that it is singular)

d) eigenvalues, eigenspaces of A

e) diagonalize A if possible and find A^{103}

f) $Ker(L)$, $Im(L)$, (sketch these subspaces) $dim(Ker(L))$, $dim(Im(L))$

g) all solutions of $L(\mathbf{x}) = (1, 2, 3, -1)$.

h) a matrix of L in a new basis $(1, 2, 0, 1)$, $(0, 0, 2, 3)$, $(1, 0, 0, 0)$, $(0, 0, 0, 1)$.

i) an orthonormal basis for $Ker(L)$ and $Im(L)$.

Do parts d)e) for matrices marked * only.

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \\ 0 & 3 & 1 & -1 \\ 0 & 5 & 6 & 0 \end{pmatrix}. \quad (*)A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

$$(*)A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 3 & 2 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}. \quad (*)A = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 6 \end{pmatrix}.$$