

Math 273 Midterm I Solutions

1. The fragment on the left computes the dot product of the vectors x and y . In MATLAB do:

```
>> p = x'*y
```

The right-hand fragment computes the outer product of the vectors x and y . In MATLAB do

```
>> a = y*x';
```

2. A quadratic equation has non-real roots when its discriminant $B^2 - 4AC$ is negative; the displayed code counts the number of times this occurs among the 1000 random samples. Vectorize the count in MATLAB by

```
>> ncomplex = sum( B.^2 - 4*A.*C < 0 );
```

3. Calculate ($h \neq 0$ is arbitrary)

$$\begin{aligned} C_h(a) &= \frac{y(a+h) - y(a-h)}{2h} \\ &= \frac{A(a+h)^2 + B(a+h) + C - (A(a-h)^2 + B(a-h) + C)}{2h} \\ &= \frac{2Aah + Bh + 2Aah + Bh}{2h} = 2Aa + B = y'(a) \end{aligned}$$

by routine algebraic expansion and simplification.

In the homework we learned that $|C_h - y'(a)| \leq M_3 h^2 / 6$ provided M_3 is a bound for y''' near a (pp. 57-58). Since y is a quadratic function, $y''' = 0$ everywhere, so we can take $M_3 = 0$ and deduce $|C_h - y'(a)| = 0$, that is, the centered difference delivers the exact derivative.

4.

- (a) We get the VanderMonde system of equations by substituting the data points into the equation $a_1 + a_2x + a_3x^2 = y$. In matrix form, the equations are:

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

- (b) This system can be solved by (for example) forming the augmented matrix and performing elimination. First subtract equation 1 from equation 2 and equation 3:

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 2 & 8 & 1 \end{array} \right]$$

Then subtract 2 times equation 2 from equation 3:

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 2 & 1 \end{array} \right]$$

Reading from bottom to top we find

$$\begin{aligned} 2a_3 &= 1, & \text{so } a_3 &= \frac{1}{2} \\ a_2 + 3 \cdot \frac{1}{2} &= 0, & \text{so } a_2 &= -\frac{3}{2} \\ a_1 + \left(-\frac{3}{2}\right) + \frac{1}{2} &= 0, & \text{so } a_1 &= 1 \end{aligned}$$

- (c) For the coefficients of the Newton form of the interpolating polynomial, substitute the data successively into the equation

$$c_1 + c_2(x - x_1) + c_3(x - x_1)(x - x_2) = y.$$

Substituting $x = 1, y = 0$ gives $c_1 = 0$.

Next, substitute $x = 2, y = 0$ and use $c_1 = 0$, to find $c_2 = 0$ also.

Finally, substituting $x = 3, y = 1, c_1 = c_2 = 0$ leads to $2c_3 = 1$, so that $c_3 = \frac{1}{2}$.

5.

- (a) If x is close to 1, the term of largest magnitude in the expansion of $p(x) = (x - 1)^6$ is $T = -20x^3$, and its magnitude is about 20.

Since IEEE long binary floating point numbers have 53 significant bits, this number system has $\beta = 2$ and $t = 53$. Now, $20 = (.101)_B \times 2^5$, so we expect (p. 46)

$$|\text{fl}(T) - T| \leq \frac{1}{2}2^{5-53} = 2^{-49} \approx 1.8 \times 10^{-15}.$$

Alternatively, by the rule of thumb used in lecture, we expect a quantity of magnitude 20 to contain roundoff error of about $20 \text{ eps} \approx 4 \times 10^{-15}$.

- (b) It matches pretty well the scale ($\pm 5 \times 10^{-15}$) in the Figure. The fluctuations in the Figure can be attributed to the random accumulation and cancellation of roundoff errors (of sizes 15 eps, 6 eps,...) from the other terms.